

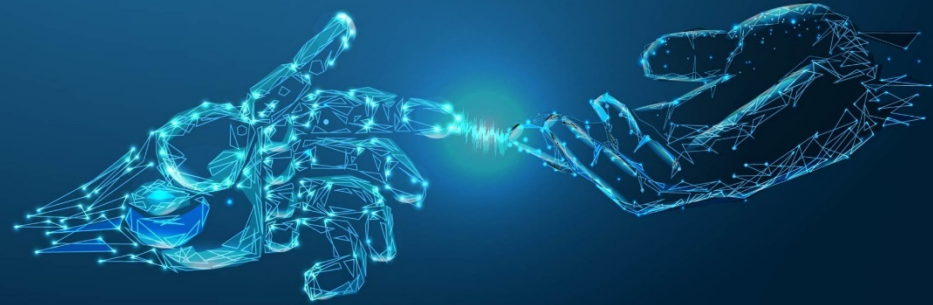


ABCDE: What to do with a predictor?

Cheng Soon Ong | 15 July 2020

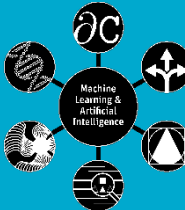
Presented to The Adecco Group
Data & AI Conference

Australia's National Science Agency



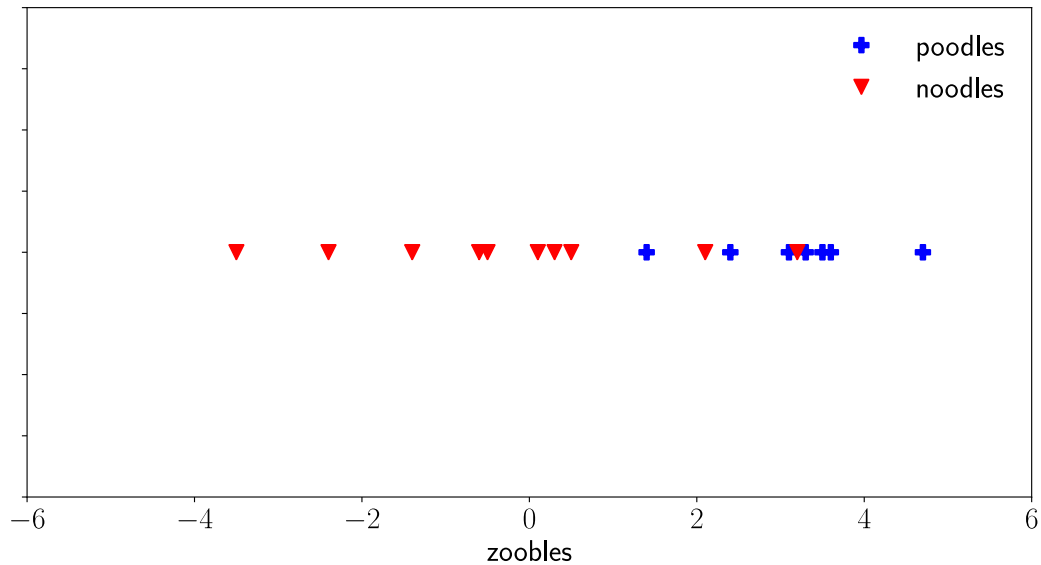
e cheng-soon.ong@data61.csiro.au
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<https://research.csiro.au/mlai-fsp/>



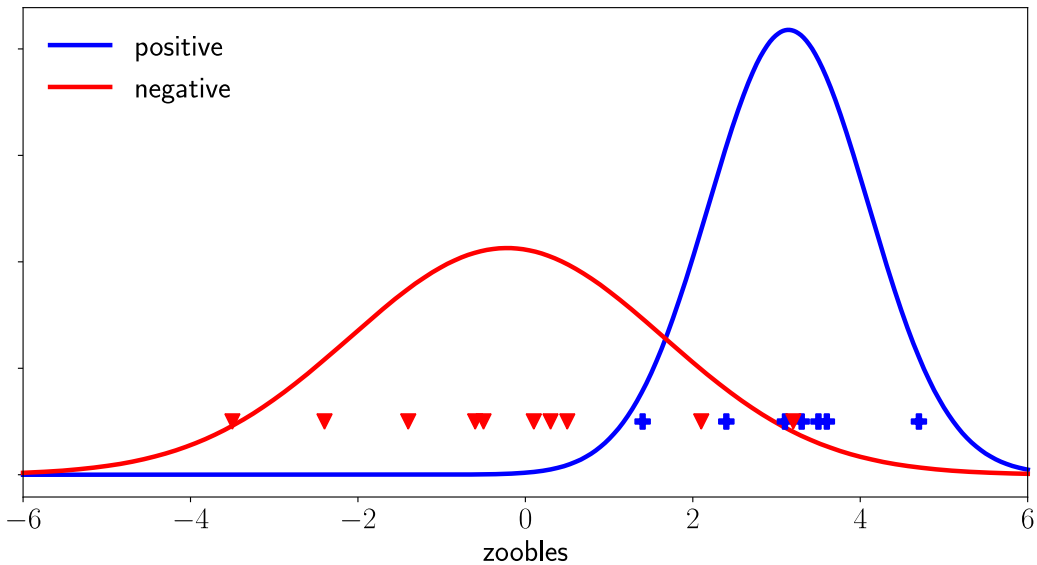
Given some data

Classify blue plus vs red triangles, based on features



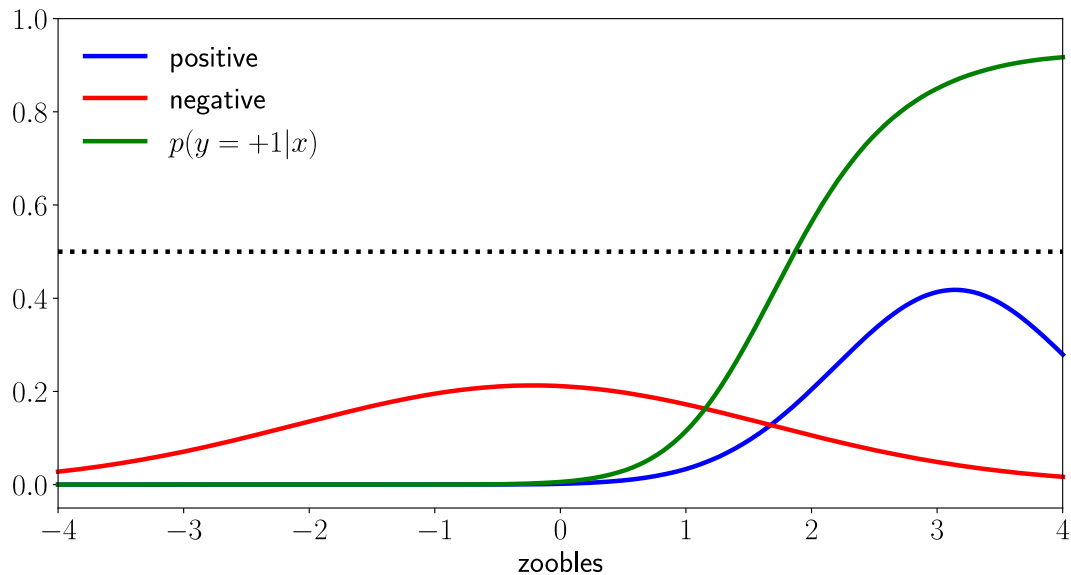
Fit a model to data

Estimate a Gaussian for each class conditional



Build a classifier

Compute the posterior probability of blue plus





What is Machine Learning?

- Machine Learning is about prediction

- Examples/covariates/features
- Labels/annotations/target variable

$$\mathbf{x}_1, \dots, \mathbf{x}_n \sim \mathcal{X}$$
$$\mathbf{y}_1, \dots, \mathbf{y}_n \sim \mathcal{Y}$$

Predictor

$$f_{\mathbf{w}}(\mathbf{x}) : \mathcal{X} \rightarrow \mathcal{Y}$$

- Estimate the best predictor = training

- No mechanistic model of the phenomenon
- There are many examples
- The outcomes (labels) are well defined (usually binary)



Who are we?

**Commonwealth Scientific and Industrial Research Organisation,
Australia**





Our research and development

We are one of the largest and most diverse scientific research organisations in the world. Our research focuses on providing solutions in nine core areas.

Key areas of research

Animals and plants

Astronomy and space

Climate

Environment

Farming and food production

Health

Information technology

Mining and manufacturing

Renewables and energy



Australia's innovation catalyst

Nurturing and enabling the
national innovation and
commercialisation ecosystem

697

Patent families

497

Active licences

\$1B+

Total market
capitalisation of
portfolio companies

170+

Start-up companies
from CSIRO science
and technology

2,400
partners

Turning science into
solutions with industry,
government and
research collaborators

150k school
students

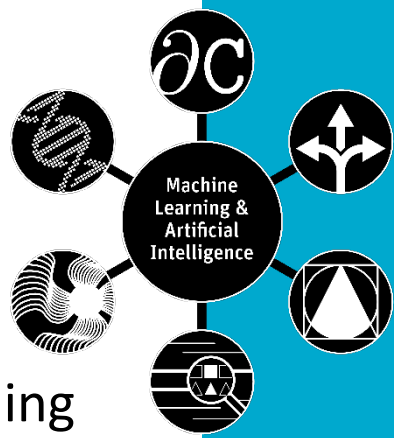
Delivering STEM
education programs to
equip Australia's future
workforce



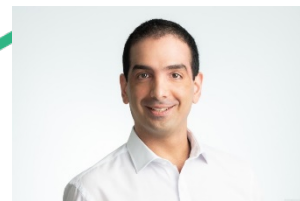
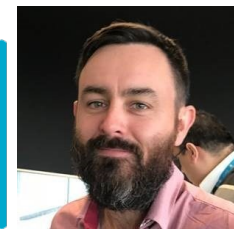
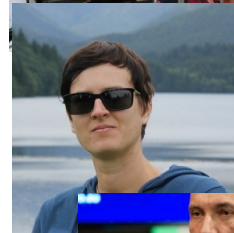
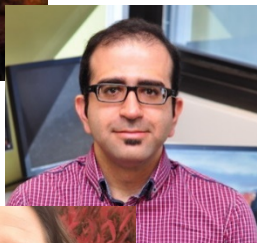
MLAI Future Science Platform

- **science**
Demonstrate machine learning for scientific discovery
- **people**
Lead a network of machine learning and science experts (create critical mass in Australia)
- **technology**
Create languages or systems to specify machine learning problems

<https://research.csiro.au/mlai-fsp/>



MLAI FSP Activities





What to do with a predictor?

What is Machine Learning?

Assume we have managed to train a sensible predictor

- Machine Learning is about prediction

- Examples/covariates/features
- Labels/annotations/target variable

$$\mathbf{x}_1, \dots, \mathbf{x}_n \sim \mathcal{X}$$
$$\mathbf{y}_1, \dots, \mathbf{y}_n \sim \mathcal{Y}$$

Predictor

$$f_w(\mathbf{x}) : \mathcal{X} \rightarrow \mathcal{Y}$$

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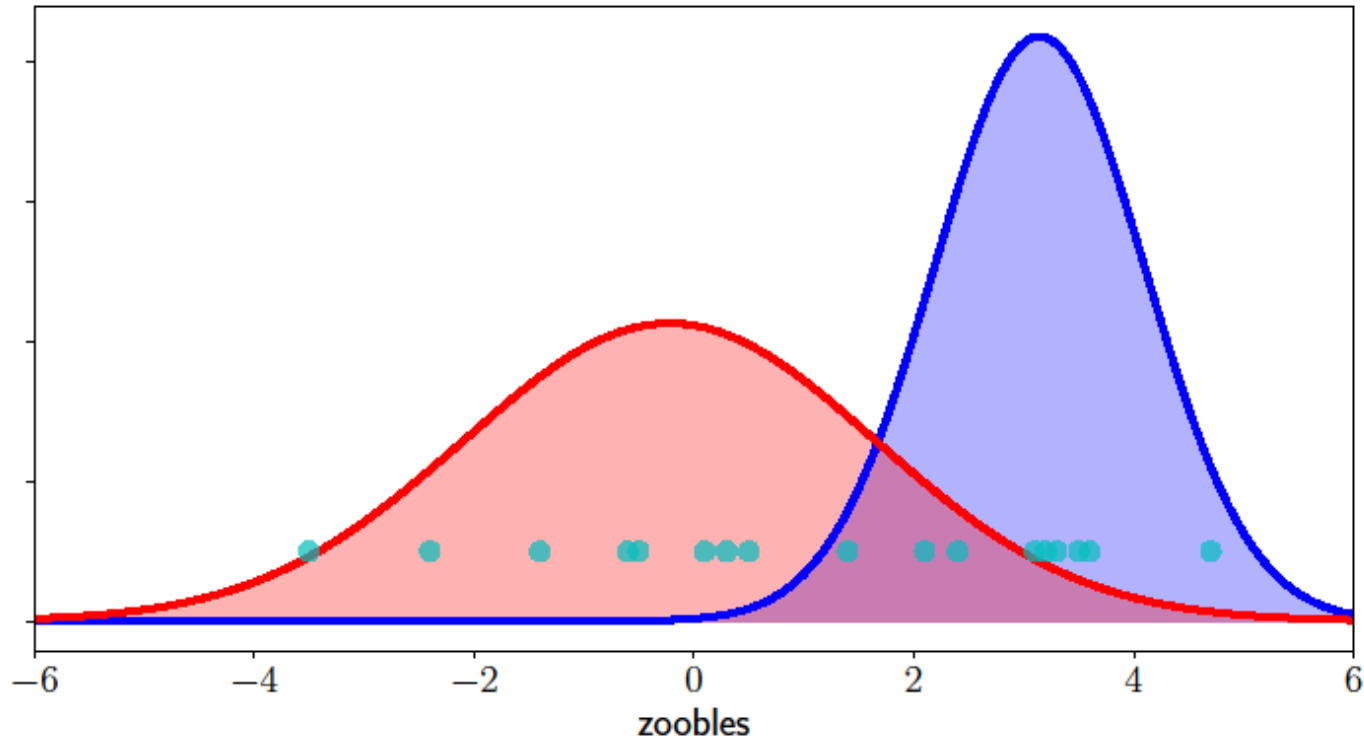


$$fw(\boldsymbol{x}) : \mathcal{X} \rightarrow \mathcal{Y}$$

- Assume that domain knowledge is captured by a predictor
- Use predictor to decide where to measure (ABCDE)
 - (A) Active Learning
 - (B) Bandits / Bayesian Optimisation
 - (C) Choice Theory
 - (DE) Design of Experiments

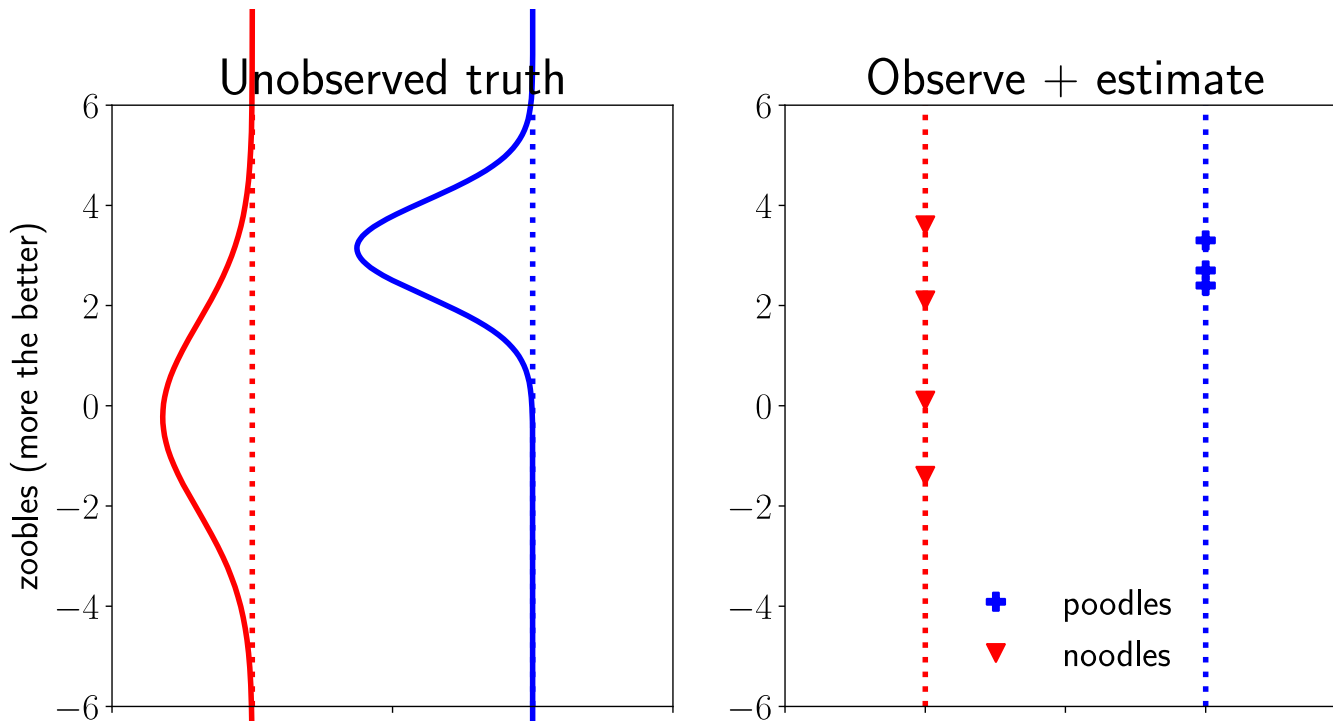
A – Active Learning

Want to build a classifier without paying for a lot of labels

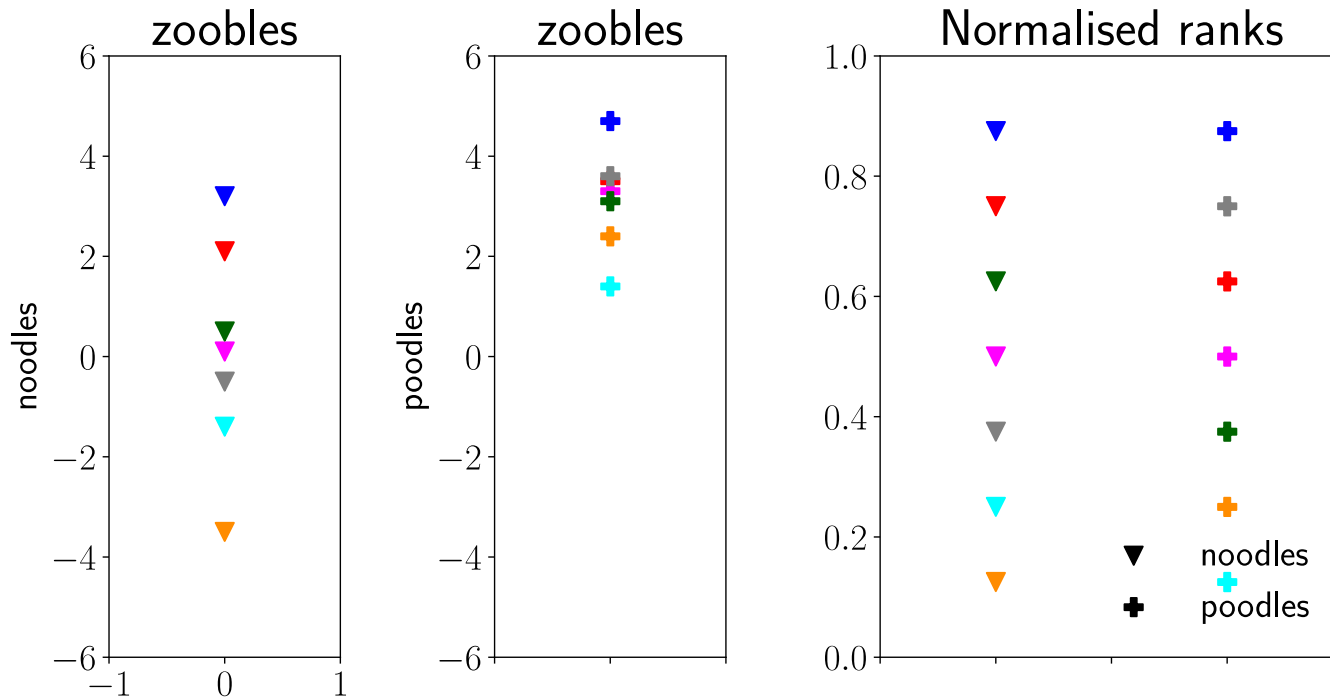


B – Bandits / Bayesian Optimisation

Want to maximise the outcome of different choices

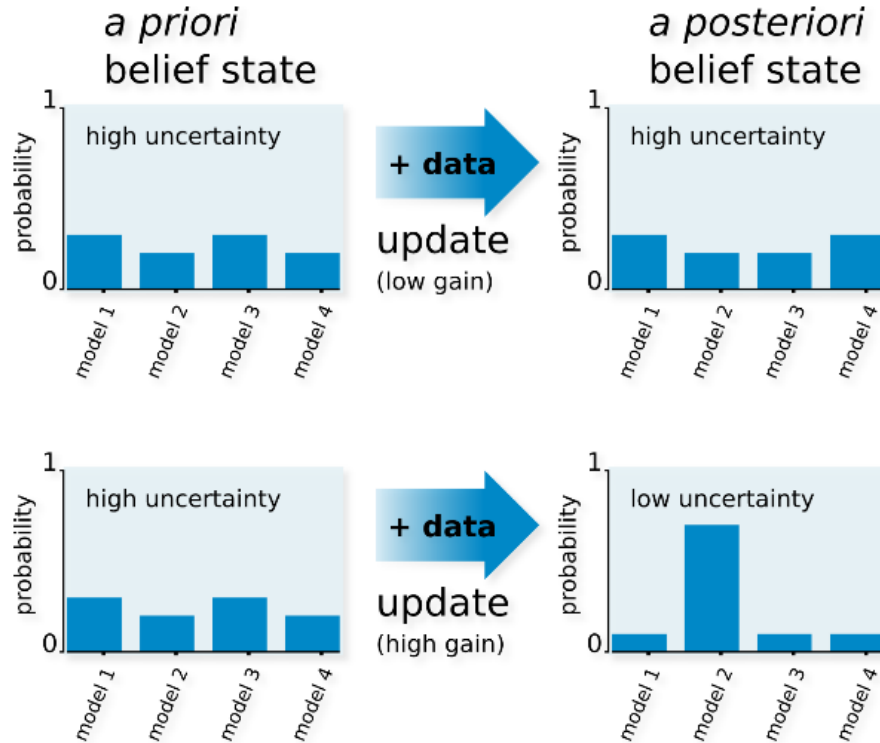


Want to integrate different sources of information



DE – Design of Experiments

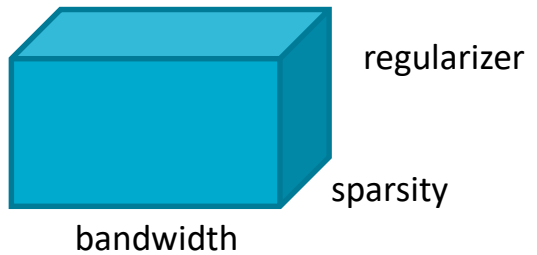
Find good models by maximizing information gain



ABCDE: what are we sorting?

A conceptual view of adaptive sampling

- Consider the set of all possible things to measure

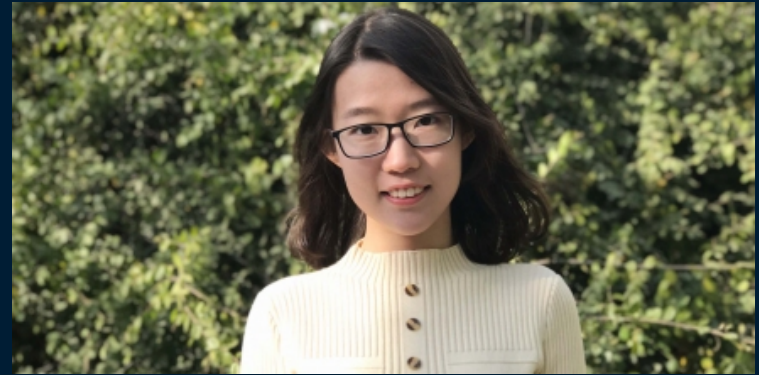


- Think of the predictor output as a generator of features
 - Each generated features demonstrates the “importance” of a sample
 - Can get multiple features by a committee or ensemble of predictors
- Adaptively choose the next thing to measure by maximising an objective
(machine learning is about defining good objective functions)

Illustration of the conceptual idea

- A – Active Learning
 1. Predictor generates a confidence that thing is positive
 2. Objective is to find the location where probability = 0.5
- B – Bandits / Bayesian Optimization
 1. Predictor generates a model of the reward
 2. Objective combines the summary statistic and uncertainty
- C – Choice Theory
 1. Predictor transforms scores into a comparable scale
 2. Objective maximises a multivariate copula score
- DE – Design of Experiments
 1. Predictor estimates the expectation over future experiments
 2. Objective identifies the notion of information gain

1. Predictor generates features
2. Define an objective function



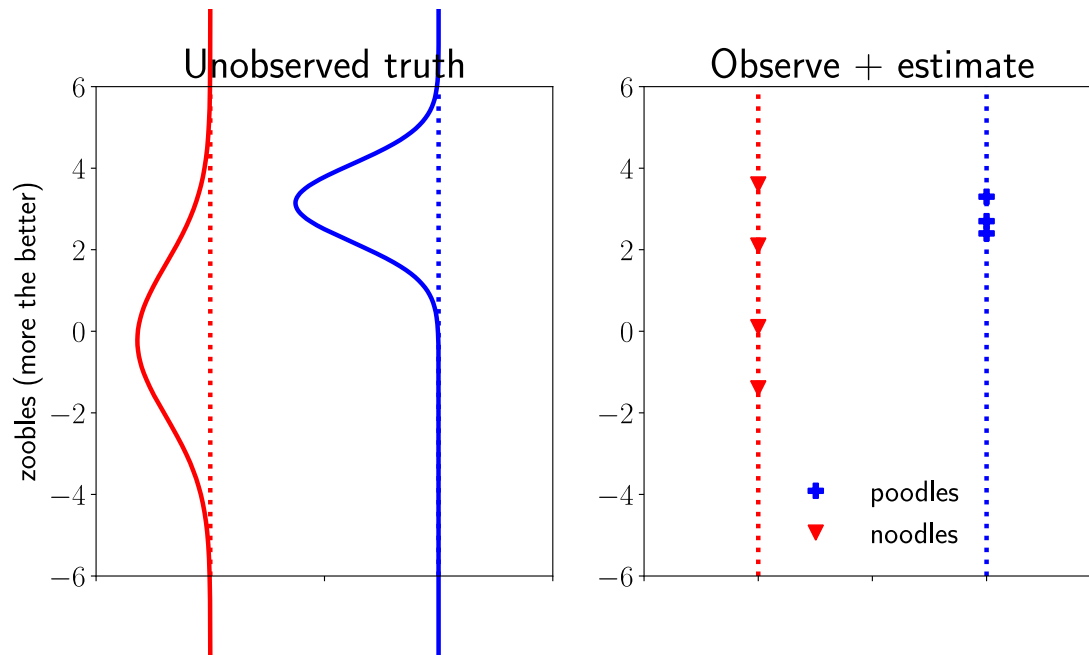
Mengyan Zhang, PhD candidate
Australian National University

Quantile Bandits

For the technical people in the audience...

B – Bandits / Bayesian Optimisation

Want to maximise the outcome of different choices

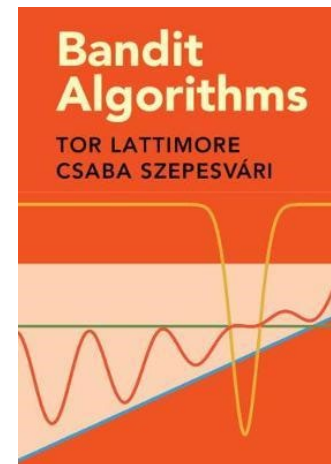




Anatomy of a Bandit Algorithm

Several design choices


- Given a set of arms, at each round:
 - Choose an arm (and get a reward)
 - depending on the task at hand
 - Estimate the distribution of the arm
 - Assumption needed for theoretical analysis
 - Usually skipped in the algorithm
 - Define a summary statistic for each distribution
 - usually the mean for risk neutral policy (Von Neumann-Morgenstern utility theory)



Anatomy of a Bandit Algorithm

Let's change from mean to quantile

- Given a set of arms, at each round:
 - Choose an arm (and get a reward)
 - depending on the task at hand
 - Estimate the distribution of the arm
 - Assumption needed for theoretical analysis
 - Usually skipped in the algorithm
 - Define a summary statistic for each distribution
 - usually the mean for risk neutral policy (Von Neumann-Morgenstern utility theory)
 - What if we are risk averse?



Replace mean
with quantiles

Bound the distance from the empirical to the true quantiles

Theorem 2 (Two-side Concentration Inequality for Quantiles). *Denote the lower bound of hazard rate as L , the number of samples as n . For all quantile level $\tau \in (0, 1)$, let $\tilde{\tau} = \tau + 1/n$, with $\tilde{k} = n(1 - \tilde{\tau})$, define $v = \frac{2}{\tilde{k}L^2}$, $c = \frac{2}{\tilde{k}L}$. Under Assumption 1, for $n > \frac{1}{1-\tau}$ and $\gamma > 0$, we have*

$$\mathbb{P} \left(\left| \hat{Q}_n^\tau - Q^\tau \right| \geq \sqrt{2v\gamma} + c\gamma \right) \leq 2 \exp(-\gamma) \quad (6)$$

- Estimate the distribution of the arm
 - Assumption needed for theoretical analysis
 - Usually skipped in the algorithm
- Define a summary statistic for each distribution
 - usually the mean for risk neutral policy (Von Neumann-Morgenstern utility theory)
 - What if we are risk averse?

Assumption 1

Non-decreasing hazard rate

Lower bound of hazard rate $L > 0$

What do we want to optimize?

Machine learning is about defining objective functions

- Given a set of arms, at each round:

- Choose an arm
 - depending on the task at hand

Objective Function

Regret minimization

Best Arm Identification

Fixed Budget

Fixed Confidence

- Estimate the distribution of the arm
 - Needed for theoretical analysis
 - Usually skipped in the algorithm
- Define a summary statistic for each distribution
 - usually the mean for risk neutral policy (Von Neumann-Morgenstern utility theory)

What if we are risk averse?

Replace mean with quantiles



Summary

A story with 3 levels ...

- Machine learning is about prediction.
 - We can use predictions to help us make decisions
 - CSIRO is using ML and AI to reimagine scientific discovery

- ABCDE: What to do with a predictor?
 - (A) Active Learning
 - (B) Bandits / Bayesian Optimisation
 - (C) Choice Theory
 - (DE) Design of Experiments

- Technical: For risk aware bandits, we can replace means with quantiles





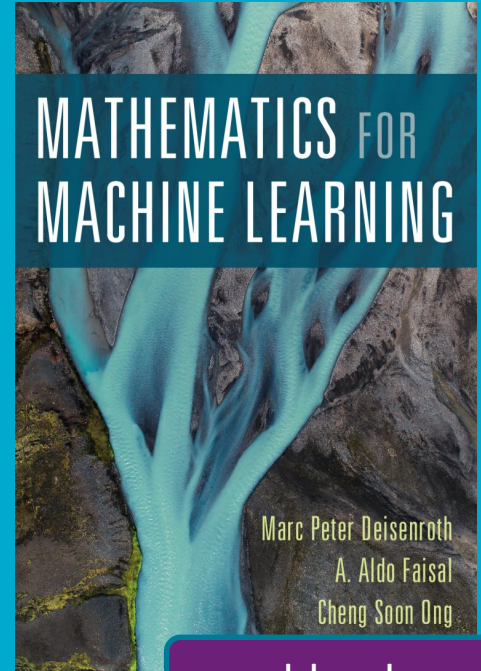
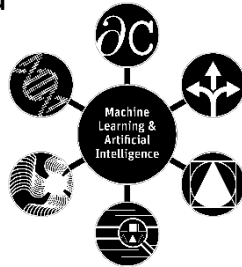
Thank you!

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